

DISCRETE WAVELET FRAMES ON THE SPHERE

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ABSTRACT

In this paper we exploit the Continuous Wavelet Transform (CWT) on the sphere introduced in [1, 2] to build the associated Discrete Wavelet Frames. We first explore half-continuous frames, i.e, frames where the position remains a continuous variable, and then move on to a fully discrete theory. This forces us to introduce the notion of controlled frames [5], which reflects the particular nature of the underlying theory, particularly the apparent conflict between dilation and the compactness of the S^2 manifold. We conclude with some numerical illustrations and future work.

1. INTRODUCTION

Many examples in physics and medicine require the existence of suitable tools for analyzing data on spherical manifolds. As an analysing tool, the CWT has many advantages over the Fourier transform, namely a locality controlled by a dilation and a translation of the wavelet. Given the CWT, designing discrete spherical wavelet frames is of paramount importance and is the main contribution of this paper.

1.1 Continuous Wavelet Transform on the Sphere

The CWT on the sphere is based on affine transformations on the sphere, namely, rotations, defined by an element ρ of the group $SO(3)$; and dilations, parametrized by a scale factor $a \in \mathbb{R}_+^*$ [1]. If $f \in L^2(S^2) \equiv L^2(S^2, d\mu)$, with the rotation invariant measure on the sphere $d\mu(\theta, \varphi) = \sin \theta d\theta d\varphi$, we have the following unitary operators:

- rotation R_ρ :

$$(R_\rho f)(\omega) = f(\rho^{-1}\omega), \omega \equiv (\theta, \varphi), \rho \in SO(3). \quad (1)$$

- dilation D_a :

$$(D_a f)(\omega) = \lambda(a, \theta)^{\frac{1}{2}} f(\omega_{1/a}), \quad a \in \mathbb{R}_+^*, \quad (2)$$

where $\omega_a \equiv (\theta_a, \varphi)$ with $\tan \frac{\theta_a}{2} = a \tan \frac{\theta}{2}$, $a > 0$, $\theta \in [0, \pi]$, $\varphi \in [0, 2\pi)$. λ is a normalization factor, given by

$$\lambda(a, \theta) = 4a^2 [(a^2 - 1) \cos \theta + (a^2 + 1)]^{-2}. \quad (3)$$

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Intuitively, the action of the dilation D_a on a function $f \in L^2(S^2)$ may be understood as follows: project f on the plane tangent at the North Pole by a stereographic projection from the South Pole, apply a Euclidian dilation by a to the projection and lift the resulting function back to the sphere by inverse stereographic projection. In the language of group theory, these two affine transformations, which do not generate a group and do not commute, belong to the conformal group of the sphere S^2 , namely, the Lorentz group $SO(3, 1)$, each subgroup being isolated via the Iwasawa decomposition (see [1] for details). Using these definitions, a square-integrable function ψ on S^2 is called an *admissible wavelet* if there is a finite constant $c \in \mathbb{R}_+^*$, such that, for all $l \in \mathbb{N}$,

$$G_\psi(l) = \frac{8\pi^2}{2l+1} \sum_{|m| \leq l} \int_{\mathbb{R}_+^*} \frac{dq}{a^3} |\widehat{\psi}_a(l, m)|^2 < c, \quad (4)$$

where $\widehat{\psi}_a(l, m) = \langle Y_l^m | \psi_a \rangle$ is the Fourier coefficient of $\psi_a = D_a \psi$. Even though this condition seems complicated and difficult to check, it can be proved that any admissible 2-D wavelet in \mathbb{R}^2 yields an admissible spherical wavelet by inverse stereographic projection. In particular, for $\phi(\theta, \varphi) = \exp(-\tan^2(\frac{\theta}{2}))$, which is the inverse stereographic projection of a Gaussian on the sphere, a simple example of admissible wavelet is the *Difference of Gaussians (DOG)* spherical wavelet

$$\psi(\theta, \varphi) = \phi(\theta, \varphi) - \frac{1}{\alpha} [D_\alpha \phi](\theta, \varphi), \quad \alpha \in \mathbb{R}_+^*. \quad (5)$$

Thus, with the given action of rotations and dilations, together with an admissible wavelet $\psi \in L^2(S^2)$, the CWT of a function $f \in L^2(S^2)$ is:

$$W_f(\rho, a) = \langle \psi_{\rho, a} | f \rangle = \int_{S^2} d\mu(\omega) f(\omega) [R_\rho D_a \psi]^*(\omega). \quad (6)$$

This last expression is nothing but a spherical correlation, i.e., $W_f(\rho, a) = (f * \psi_a^*)(\rho)$.

The following proposition shows that the family of rotated and translated wavelets forms a continuous frame in $L^2(S^2)$, from which we derive a reconstruction formula:

Proposition 1 *Let $f \in L^2(S^2)$. If ψ is an admissible wavelet such that $\int_{S^2} d\varphi \psi(\theta, \varphi) \neq 0$, then*

$$f(\omega) = \int_{\mathbb{R}_+^*} \int_{SO(3)} \frac{d\text{adv}(\rho)}{a^3} W_f(\rho, a) [R_\rho L_\psi^{-1} D_a \psi](\omega), \quad (7)$$

where the coefficients are given by (6), L_ψ is the **frame operator** defined by

$$[\widehat{L_\psi h}](l, m) = G_\psi(l) \widehat{h}(l, m), \quad \forall h \in L^2(S^2), \quad (8)$$

and $G_\psi(l)$ is defined by (4).

The spherical CWT defines an isometry, given by the following result:

Corollary 1 *Under the condition of the previous proposition, the following Plancherel relation is satisfied*

$$\|f\|_2^2 = \int_{\mathbb{R}_+^*} \int_{SO(3)} \frac{d\text{adv}(\rho)}{a^3} W_f(\rho, a) \tilde{W}_f^*(\rho, a) \quad (9)$$

where

$$\tilde{W}_f(\rho, a) = \langle \tilde{\psi}_{\rho, a} | f \rangle = \langle R_\rho L_\psi^{-1} D_a \psi | f \rangle. \quad (10)$$

The proof of these results and more details on the CWT on the sphere and its implementation can be found in [2]

Since the stereographic dilation is radial around the North Pole $\eta \in S^2$, an axisymmetric wavelet ψ on S^2 , i.e., invariant under rotation around η , remains axisymmetric through dilation. So, if a rotation $\rho \in SO(3)$ is decomposed in terms of its Euler angles $\varphi, \theta, \alpha \in S^1$, i.e., $\rho = \rho(\varphi, \theta, \alpha)$, then $R_\rho \psi_a = R_{[\omega]} \psi_a$, where $[\omega] = \rho(\varphi, \theta, 0) \in SO(3)$ is the result of two consecutive rotations, and moves η to $\omega = (\theta, \varphi) \in S^2$. Consequently, the CWT is redefined on $S^2 \times \mathbb{R}_+^*$ by

$$W_f(\omega, a) \equiv (f * \psi_a^*)([\omega]) \equiv (f * \psi_a^*)(\omega), \quad a \in \mathbb{R}_+^*. \quad (11)$$

In that particular case, the reconstruction formula (9) becomes

$$f(\omega) = \int_{\mathbb{R}_+^*} \int_{S^2} \frac{d\text{adv}(\omega')}{a^3} W_f(\omega', a) \tilde{\psi}_{\omega, a}(\omega'), \quad (12)$$

with $\tilde{\psi}_{\omega, a} = R_{[\omega]} L_\psi^{-1} D_a \psi$, and where L_ψ is the frame operator defined in (8) with G_ψ reduced now to

$$G_\psi(l) = \frac{4\pi}{2l+1} \int_{\mathbb{R}_+^*} \frac{da}{a^3} |\hat{\psi}_a(l, 0)|^2. \quad (13)$$

2. DISCRETE WAVELET FRAMES ON THE SPHERE

In this section, we describe under which conditions the parameters of the continuous wavelet transform can be discretized. We focus on the case of axisymmetric wavelets.

2.1 Half-continuous Spherical Frame

2.1.1 First Approach

We propose now to discretize the scale of the CWT on the sphere as we let the position vary continuously. In other words, we choose the parameterization

$$\omega \in S^2 \quad (14)$$

$$a \in A \equiv \{a_j \in \mathbb{R}_+^* : j \in \mathbb{Z}, a_j > a_{j+1}\}, \quad (15)$$

which generates the half-continuous grid

$$\Lambda(A) = \{(\omega, a_j) : \omega \in S^2, j \in \mathbb{Z}\}. \quad (16)$$

In order to have a reconstruction for every function $f \in L^2(S^2)$, a first possible approach would be to impose

$$m \|f\|_2^2 \leq \sum_{j \in \mathbb{Z}} v_j \int_{S^2} d\mu(\omega) |W_f(\omega, a_j)|^2 \leq M \|f\|_2^2, \quad (17)$$

with $m, M \in \mathbb{R}_+^*$ independent of f , and for some weights $v_j > 0$ taking into account the discretization of the continuous measure $a^{-3} da$. In this case, the family

$$\{\psi_{\omega, a_j} = R_{[\omega]} D_{a_j} \psi : (\omega, a_j) \in \Lambda(m)\}, \quad (18)$$

constitutes a half-continuous frame in $L^2(S^2)$. The following proposition translates this last condition into the Fourier space (as defined by the spherical harmonics).

Proposition 2 *If there are two constants $m, M \in \mathbb{R}_+^*$ such that*

$$m \leq \frac{4\pi}{2l+1} \sum_{j \in \mathbb{Z}} v_j |\hat{\psi}_{a_j}(l, 0)|^2 \leq M \quad (19)$$

for all $l \in \mathbb{N}$, then (17) is fulfilled.

Let us choose a DOG wavelet ($\alpha = 1.25$) and a discretized dyadic scale with a certain number of voices $K \in \mathbb{N}^0$, namely

$$a_j = a_0 2^{-j/K}, \quad j \in \mathbb{Z}. \quad (20)$$

For the sake of simplicity, we replace the indices a_j by j . Moreover, we choose weights v_j that take into account the discretization of the continuous measure $\frac{da}{a^3}$, which means

$$v_j = \frac{a_j - a_{j+1}}{a_j^3} = a_j^{-2} \left(\frac{2^{1/K} - 1}{2^{1/K}} \right). \quad (21)$$

We have estimated the bounds m and M , respectively, from the minimum and the maximum of the quantity

$$S(l) = \frac{4\pi}{2l+1} \sum_{j \in \mathbb{Z}} v_j |\hat{\psi}_j(l, 0)|^2, \quad (22)$$

over $l \in [0, 31]$ and for $K \in [1, 4]$. The results are shown in Table 1(a).

K	m	M	M/m
1	0.5281	0.9658	1.8288
2	0.6817	1.1203	1.8107
3	0.6537	1.1836	1.8107
4	0.6722	1.2171	1.8107

(a)

K	m	M	M/m
1	0.7313	0.7628	1.0431
2	0.8747	0.8766	1.0021
3	0.9242	0.9254	1.0014
4	0.9503	0.9512	1.0009

(b)

Table 1: Estimation of the bounds m and M as a function of the extrema of $S(l)$ for some values of K . (a) First approach. (b) Second approach.

We can see that for $K > 2$, the ratio M/m converges toward the value 1.8107. So, it does not converge toward a tight frame, for which $m = M$. This is mainly due to a non-vanishing ‘‘gap’’ in the graph of $S(l)$ for small values of l .

2.1.2 Second Approach

Trying to converge to a tight frame, we adopt now a second approach for our half-continuous discretization. We start from the Plancherel relation as defined in Corollary 1. In other words, we will observe under which conditions we obtain a *controlled* frame [5]. That is, for two frame bounds $m, M \in \mathbb{R}_+^*$, we want

$$m \|f\|_2^2 \leq \sum_{j \in \mathbb{Z}} v_j \int_{S^2} d\mu(\omega) |W_f \tilde{W}_f^*(\omega, a_j)|^2 \leq M \|f\|_2^2, \quad (23)$$

where $f \in L^2(S^2)$, $\widetilde{W}_f(\omega, a_j) = \langle R_{[\omega]} L_\psi^{-1} D_a \psi | f \rangle$, and where the brackets mean multiplication of two functions. The operator L_ψ controls the frame and it is bounded with bounded inverse if and only if the wavelet ψ is admissible.

Proposition 3 *If there exist two constants $m, M \in \mathbb{R}_+^*$ such that*

$$m \leq \frac{4\pi}{2l+1} G_\psi(l)^{-1} \sum_{j \in \mathbb{Z}} v_j |\widehat{\psi}_j(l, 0)|^2 \leq M, \quad (24)$$

with $G_\psi(l)$ given by (13) and for all $l \in \mathbb{N}$, then (23) is verified.

By using the same scale discretization, the same wavelet and the same weights v_j as in the first approach, we find now (see Table 1(b)) that for $l \in [0, 31]$, the ratio M/m tends to 1 as K increases. A tight frame is thus reachable by considering the controlled frame approach.

2.1.3 Construction of a tight half-continuous frame

It is possible to build a tight half-continuous frame on the sphere using the previous considerations.

Proposition 4 *Let $A \equiv \{a_j : j \in \mathbb{Z}, a_j > a_{j+1}\}$ be a sequence of scales. If ψ is an axisymmetric wavelet such that*

$$g_\psi(l) = \frac{4\pi}{2l+1} \sum_{j \in \mathbb{Z}} v_j |\widehat{\psi}_j(l, 0)|^2 \neq 0, \quad \forall l \in \mathbb{N}, \quad (25)$$

then,

$$f(\omega) = \sum_{j \in \mathbb{Z}} v_j [W_f(\cdot, a_j) \star \psi_j^\#](\omega), \quad (26)$$

where $\psi_j^\# = l_\psi^{-1} D_{a_j} \psi$ and l_ψ is the operator defined in the Fourier domain by $l_\psi^{-1} h(l, m) = g_\psi^{-1}(l) h(l, m)$. In other words, the frame controlled by l_ψ is tight.

The new operator l_ψ is simply the discretization of A of L_ψ as defined in (13).

Notice that one can introduce a scaling function ζ such that

$$|\widehat{\zeta}(l, m)|^2 = \delta_{m,0} \sum_{j=-\infty}^{-1} v_j |\widehat{\psi}_j(l, 0)|^2, \quad (27)$$

so that

$$f(\omega) = [S_f \star \zeta^\#](\omega) + \sum_{j \in \mathbb{N}} v_j [W_f(\cdot, a_j) \star \psi_j^\#](\omega), \quad (28)$$

with $S_f(\omega) = \langle R_{[\omega]} \zeta | f \rangle$ and $\zeta^\# = l_\psi^{-1} \zeta$.

2.2 Discrete Spherical Frames

In this section, we will completely discretize the CWT on the sphere. The scales are discretized as previously, namely

$$a \in A = \{a_j \in \mathbb{R}_+^* : a_j > a_{j+1}, j \in \mathbb{Z}\}, \quad (29)$$

and the positions are taken in an equi-angular grid \mathcal{G}_j indexed by the scale level, related to the scale in such a way that $\omega \in \mathcal{G}_j$, with

$$\mathcal{G}_j = \{(\theta_{jp}, \varphi_{jq}) \in S^2 : \theta_{jp} = \frac{(2p+1)\pi}{4B_j}, \varphi_{jq} = \frac{q\pi}{B_j}\}, \quad (30)$$

$p, q \in \mathcal{N}_j \equiv \{n \in \mathbb{N} : n < 2B_j\}$ and for some range of bandwidths $B = \{B_j \in 2\mathbb{N}, j \in \mathbb{Z}\}$. Actually, θ_{jp} form a *pseudo-spectral* grid and are localized on the knots of a Chebishev polynomial of order $2B_j$ [3, 4]. With this choice, for certain weights $w_{jp} > 0$ and on every grid \mathcal{G}_j , the following quadrature rule is verified [4]:

$$\int_{S^2} d\mu(\omega) f(\omega) = \sum_{p, q \in \mathcal{N}_j} w_{jp} f(\omega_{jpq}), \quad (31)$$

with $\omega_{jpq} = (\theta_{jp}, \varphi_{jq})$ and for every band-limited function $f \in L^2(S^2)$ of bandwidth B_j , i.e., such that $\widehat{f}(l, m) = 0$ for all $l \geq B_j$.

The complete space of the discretization is finally

$$\Lambda(A, B) = \{(a_j, \omega_{jpq}) : j \in \mathbb{Z}, p, q \in \mathcal{N}_j\}. \quad (32)$$

In this case, for an axisymmetric and admissible mother wavelet $\psi \in S^2$, the family of wavelets

$$\{\psi_{jpq} = R_{[\omega_{jpq}]} D_{a_j} \psi : j \in \mathbb{Z}, p, q \in \mathcal{N}_j\} \quad (33)$$

constitutes a weighted frame controlled by the operator L_ψ , if there exist two constants $m, M \in \mathbb{R}_+^*$ such that, for any function $f \in L^2(S^2)$, we have

$$m \|f\|_2^2 \leq \sum_{j \in \mathbb{Z}} \sum_{p, q \in \mathcal{N}_j} v_j w_{jp} [W_f \widetilde{W}_j^*](\omega_{jpq}, a_j) \leq M \|f\|_2^2, \quad (34)$$

In the last expression, the values $v_j w_{jp}$ replace the measure $a^{-3} da d\mu(\theta, \varphi)$.

Proposition 5 *Let the discretized grid $\Lambda(A, B)$ be given as in (32). Let ψ be an axisymmetric and admissible wavelet on S^2 , and*

$$S'(l) = \sum_{j \in \mathbb{Z}} \frac{4\pi v_j}{2l+1} \mathbb{1}_{[0, B_j]}(l) G_\psi^{-1}(l) |\widehat{\psi}_j(l, 0)|^2, \quad (35)$$

$$\delta = \|\mathcal{X}\| \equiv \sup_{(H)_l \in \mathbb{N}} \frac{\|\mathcal{X}H\|}{\|H\|}, \quad (36)$$

with the infinite matrix $(\mathcal{X}_{l'l'})_{l, l' \in \mathbb{N}}$ given by

$$\mathcal{X}_{l'l'} = \sum_{j \in \mathbb{N}} c_j(l, l') \mathbb{1}_{[2B_j, +\infty]}(l+l') |\widehat{\psi}_j(l, 0)| |\widehat{\psi}_j(l', 0)| \quad (37)$$

and $c_j(l, l') = \frac{2\pi v_j}{B_j} G_\psi^{-1}(l) [(2(l+B_j)+1)(2(l'+B_j)+1)]^{\frac{1}{2}}$.

If we have

$$0 \leq \delta < K_0 \leq K_1 < \infty, \quad (38)$$

with $K_0 = \inf_{l \in \mathbb{N}} S'(l)$ and $K_1 = \sup_{l \in \mathbb{N}} S'(l)$, then the family (33) is a weighted spherical frame controlled by the operator L_ψ with frames bounds $K_0 - \delta$, $K_0 + \delta$.

A detailed proof of this proposition can be found in [5].

The evaluation of $\|\mathcal{X}\|$ could be complicated when the matrix \mathcal{X} is infinite. However, in practice, we work with band-limited functions $f \in L^2(S^2)$ of bandwidth $b \in \mathbb{N}^0$. Consequently, $\|\mathcal{X}\|$ could be replaced by the norm of the finite matrix $(\mathcal{X}_{l'l'})_{0 \leq l, l' < b}$.

We have estimated the bounds of a spherical DOG wavelet frame in the case $b = 64$, using a dyadically discretized scale (with $K = a_0 = 1$ in (20)), while the bandwidth, associated to the grid size supporting each resolution j , was fixed to

$$B_j = B_0 2^{|j|}, \quad B_0 \in \mathbb{N}, \quad (39)$$

where B_0 is the minimal bandwidth associated to ψ_1 . The last equation takes into account the particular nature of the stereographic dilation on S^2 . Indeed, for the DOG wavelet, we may show that the (essential) support of $\hat{\psi}_j$ increases with j if $j > 0$, and grows with $-j$ if $j \leq 0$ [5].

Table 2 presents the results of the evaluation of K_0 , K_1 and δ as well as the bounds of the associated frames.

	K_0	K_1	δ	$m = K_0 - \delta$	$M = K_1 + \delta$	M/m
$B_0 = 2$	0.6807	0.7700	84.1502	—	—	—
$B_0 = 4$	0.7402	0.7790	0.0594	0.6808	0.8384	1.2314
$B_0 = 8$	0.7402	0.7790	0.0014	0.7388	0.7804	1.0564

Table 2: Evaluation of K_0 , K_1 and δ on the functions $f \in L^2(S^2)$ at bandwidth 64.

One can see that for $B_0 \geq 4$, condition (38) is reached. However, a tight frame cannot be obtained by increasing B_0 . Actually, if B_0 tends to infinity, the spherical grids at each resolution get finer and finer and we approach the half-continuous frames, but as seen in the previous section, the one voice discretization of the scale is not sufficient.

3. EXAMPLES AND IMPLEMENTATIONS

The next application shows the advantages of the half-continuous frame decomposition over methods constructed completely in the frequency domain. We work on a cartography of the surface of Jupiter and we want to locally enhance the details in a neighborhood of its Red Spot. All the spherical correlations defining the wavelet coefficients and the reconstruction (28) have been performed in Fourier space using the spherical correlation theorem [4]

$$\widehat{f \star g}(l, m) = \sqrt{\frac{4\pi}{2l+1}} \widehat{f}(l, m) \widehat{g}(l, 0), \quad (40)$$

for $f \in L^2(S^2)$ and for any axisymmetric function $g \in L^2(S^2)$, and by using the SpharmonicKit [6] which performs fast (forward and inverse) spherical harmonics transforms. All these methods are incorporated into the Matlab©YAWtb toolbox¹.

We consider an equi-angular grid of size is 512×512 and the data bandwidth is set to $b = 256$. In this context the DOG wavelet is properly discretized for a scale range with $|j| \leq 7$ and $a_0 = 1$.

We proceed as follows: Before reconstruction, the coefficients at the finer scale $W_f(\omega, a_7)$ are multiplied by a mask function that increases their amplitudes in a vicinity of the Red Spot. The rest of the coefficients are not modified.

Results after reconstruction are shown in Figure 1. We show a zoom over the Red Spot of the reconstructed signal without any processing (left) and the modified version where the Red Spot's details are clearly sharper (right).

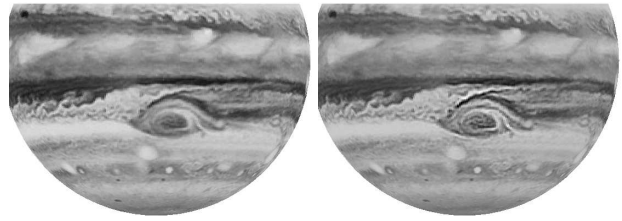


Figure 1: Enhancement of the details of Jupiter's Red Spot: zoom over the spot (left); zoom over the spot with sharper details (right).

4. CONCLUSIONS AND FUTURE WORK

Conditions on the existence of half-continuous and discrete spherical frames have been established from the (stereographic) spherical CWT [1]. The last section illustrates the efficiency of a particular DOG (half-continuous) tight frame with a simple Jovian image enhancing. An example of a discrete frame using the results of Proposition 5 has still to be designed. These techniques could serve for instance to discover the Gaussian anisotropies in the astronomical *Cosmic Microwave Background* [7], or to track the orientations in \mathbb{R}^3 of fibres in the human brain connectivity [8]. Work in these directions is currently in progress.

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¹Developed by some of us and freely (GPLly) available at <http://www.fjma.ucl.ac.be/projects/yawtb>.